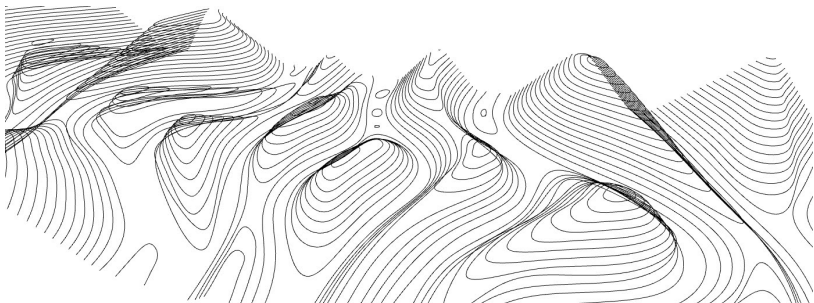


ODEs from a geometric viewpoint

Antonio J. Pan-Collantes

October 15, 2021



Index

- 1 Introduction
- 2 Lie approach and solvable structures
 - Lie symmetries
 - Solvable structures
- 3 C^∞ -symmetries and beyond
- 4 Bibliography

ODEs

Equation:

$$u^{(m)}(x) = F(x, u(x), u'(x), \dots, u^{(m-1)}(x)) \text{ and}$$

$$\begin{cases} u(0) = c_0, \\ u'(0) = c_1 \\ \dots \\ u^{(m-1)}(0) = c_{m-1} \end{cases}$$

where $F : \mathbb{R}^{m+1} \rightarrow \mathbb{R}$ with conditions...

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Solutions:

$$\exists u : D \subseteq \mathbb{R} \rightarrow \mathbb{R}?$$

Flow of vector fields

Fundamental theorem on flows

Given a vector field X on \mathbb{R}^n , then X has a unique maximal flow

$$\phi_t^X : U \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^n$$

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Vector fields \iff local groups of transformations.

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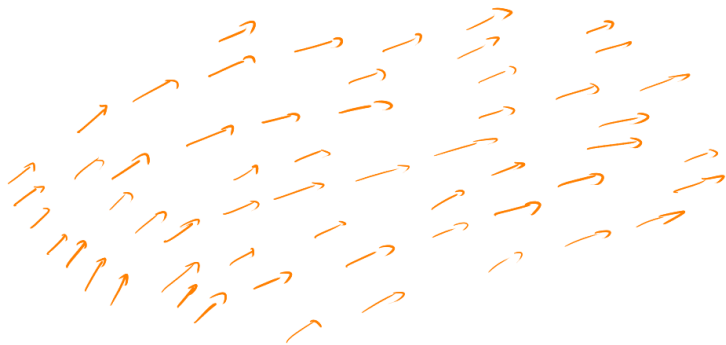
Vector fields \iff local groups of transformations.

ODE Existence, Uniqueness and Smoothness

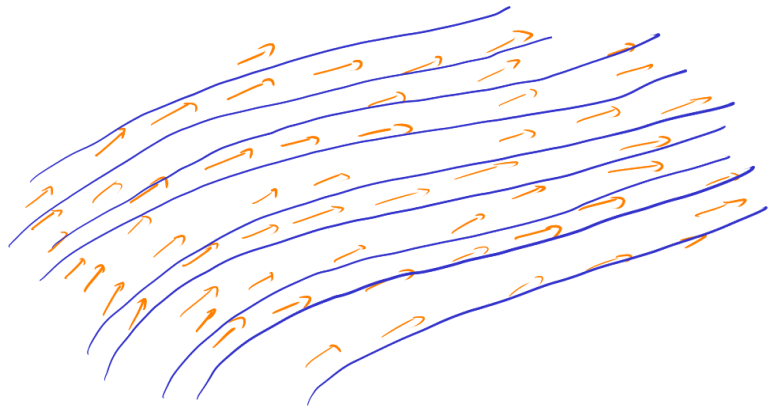
$$\begin{cases} \dot{x}_1(t) &= V_1(x_1, \dots, x_n) \\ \dots &= \dots \\ \dot{x}_n(t) &= V_n(x_1, \dots, x_n) \end{cases}$$

[Lee, 2013], [Olver, 1986]

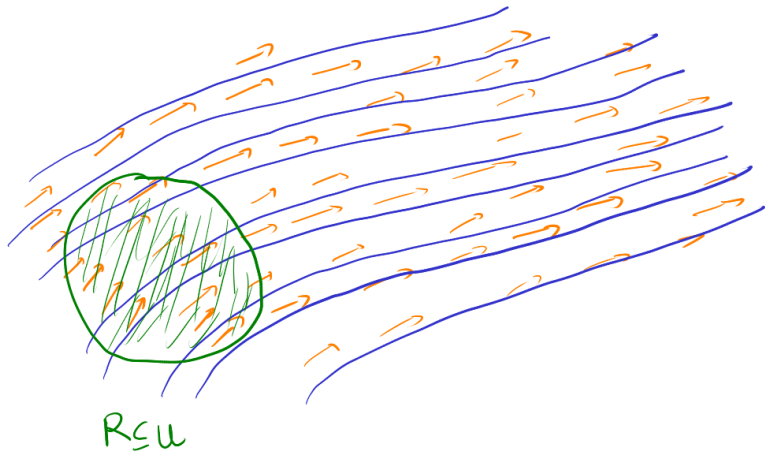
Visualization



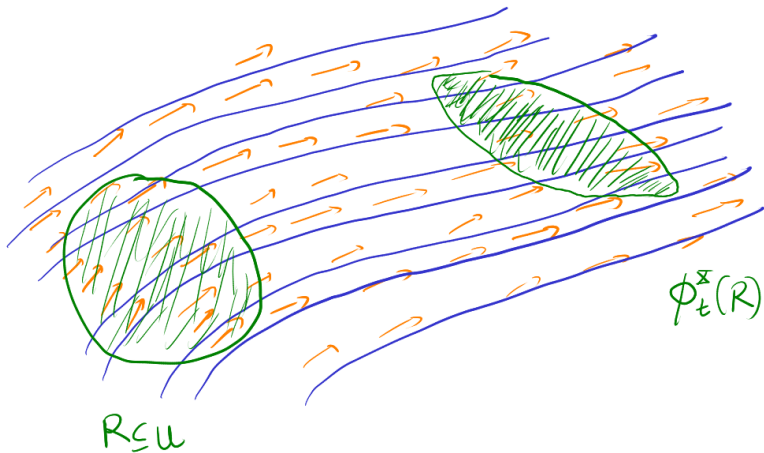
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Linkage?

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Lie ideas

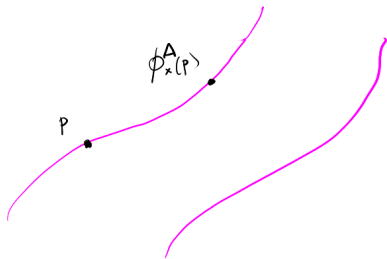
Lie point symmetry

A local 1-parameter group Ψ_t is a Lie point symmetry if it transforms solutions into solutions

Lie ideas

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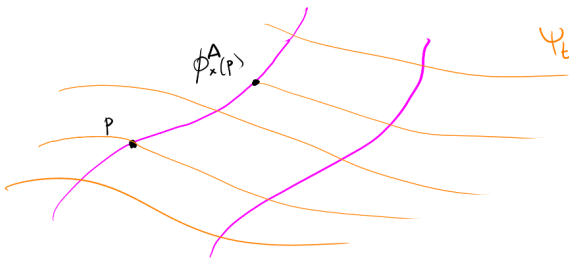
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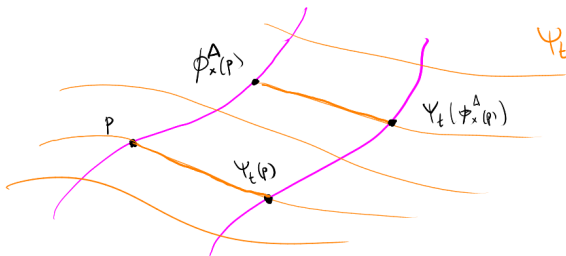
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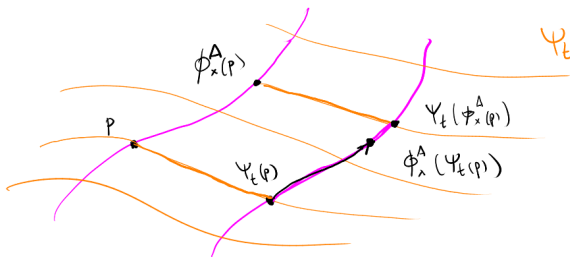
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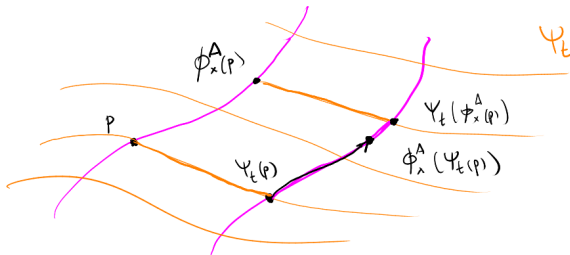
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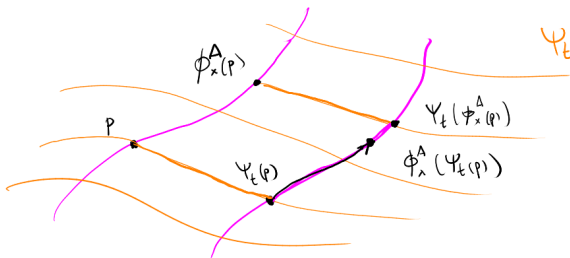


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$$\phi_x^A(\Psi_t(p)) \neq \Psi_t(\phi_x^A(p)) \Rightarrow [X, A] = \alpha \cdot A$$

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From our point of view

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Family of lines from family of equations

$$\begin{vmatrix} 1 & dx \\ F & du \end{vmatrix} = -Fdx + du = 0$$

Is this 1-form exact?

Exact 1-form

There exists a function $G : \mathbb{R}^2 \rightarrow \mathbb{R}$ such that $dG = -Fdx + du$

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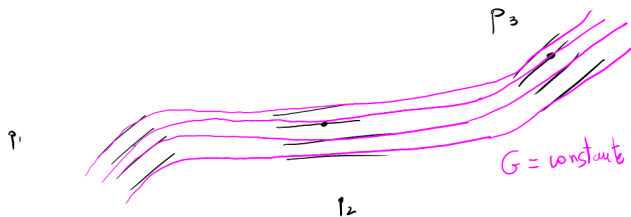
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 P_1  P_2 P_3 

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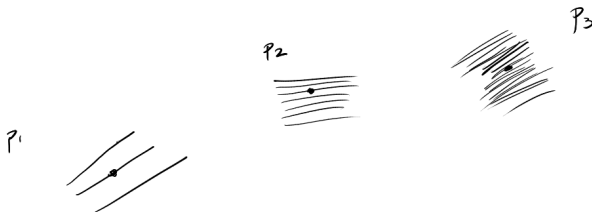
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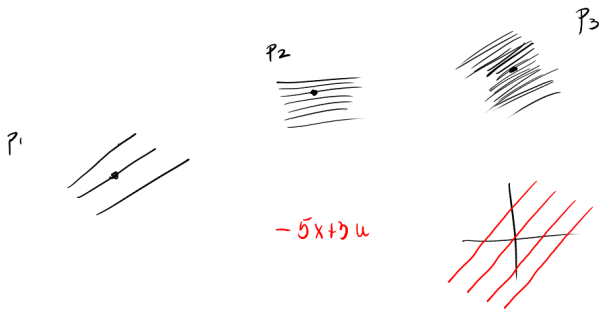
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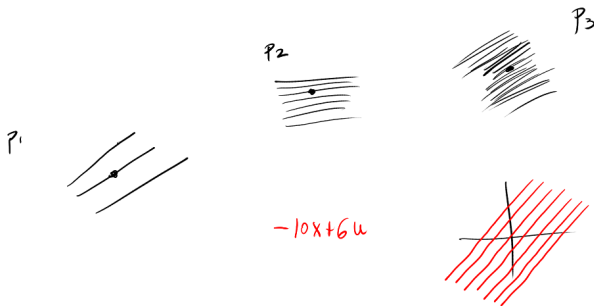
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Integrating factor

μ such that there exists G with $dG = \mu(-Fdx + du)$

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Key result

If X is a Lie symmetry for A then

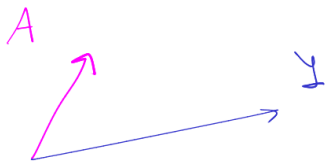
$$\frac{1}{\det(A, X)}$$

is an integrating factor for $-Fdx + du$, or in other words,

$$\omega = \frac{\det(A, -)}{\det(A, X)}$$

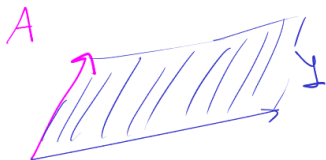
is exact (locally).

Idea of the proof



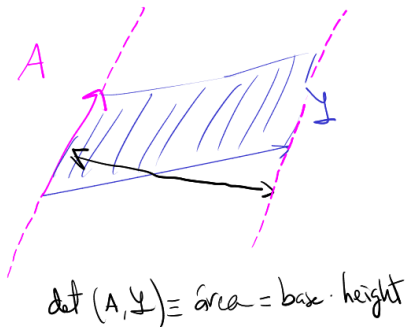
$$\det(A, Y)$$

Idea of the proof

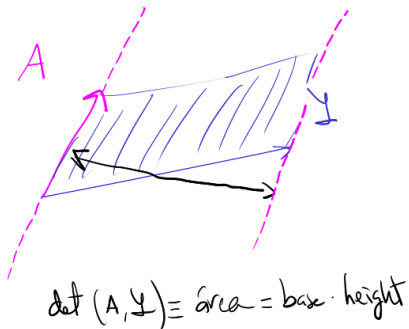


$$\det(A, y) \equiv \text{area}$$

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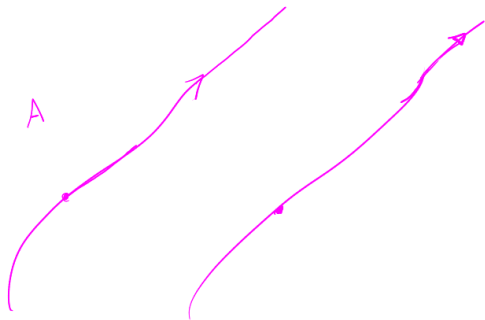


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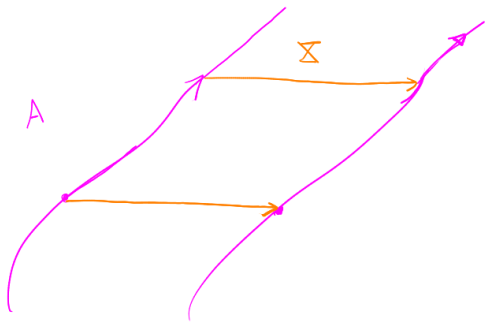


But base changes when
we move along
solution curves!

Idea of the proof

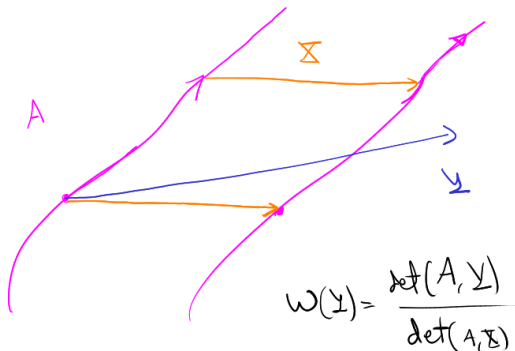


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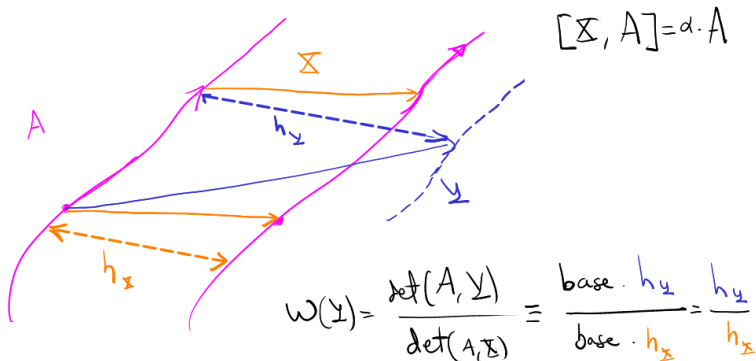
$$[X, A] = d.A$$

Idea of the proof



$$[X, A] = a \cdot A$$

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Solvable structures: [Basarab-Horwath, 1991]

- Symmetries of involutive distributions instead of vector fields

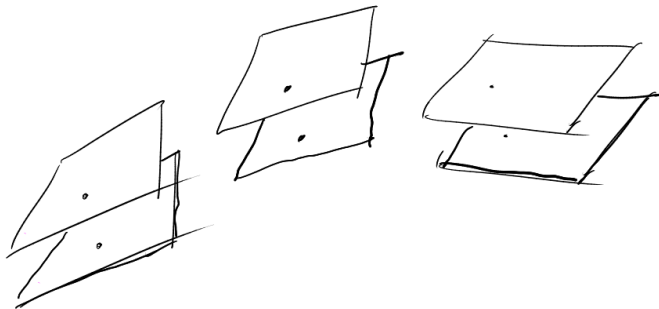
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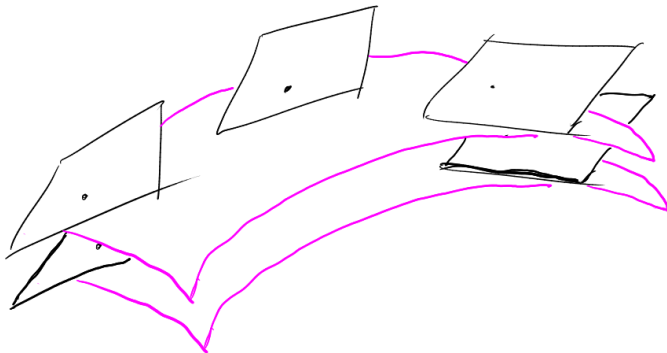
Solvable structures: [Basarab-Horwath, 1991]

- Symmetries of involutive distributions instead of vector fields
- Given A , we aim to an ordered collection $\langle X_1, \dots, X_k \rangle$ such that X_j is symmetry of the "previous distribution".

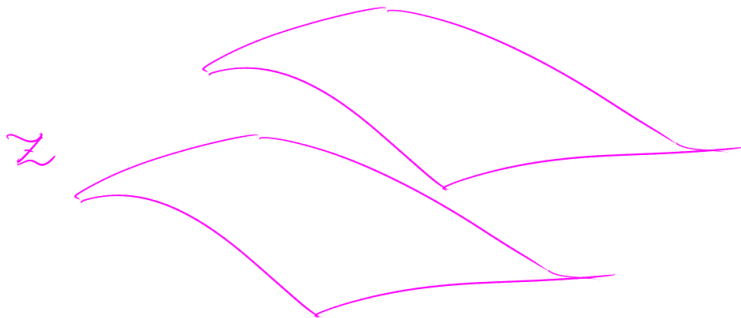
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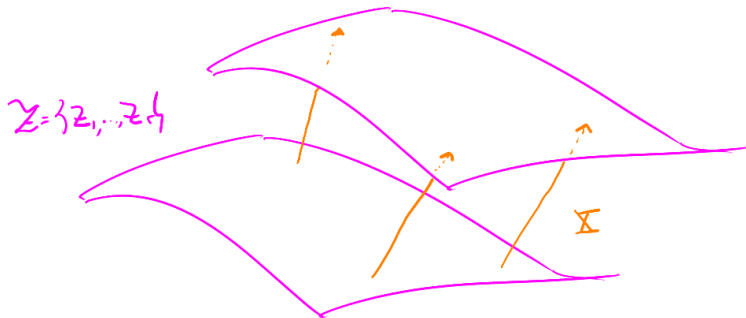
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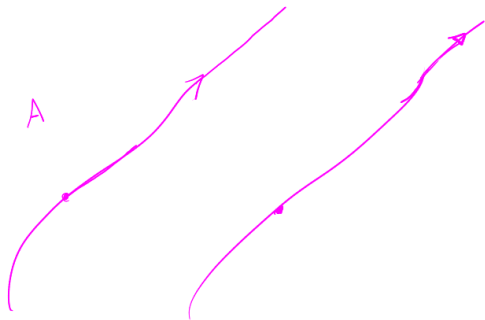


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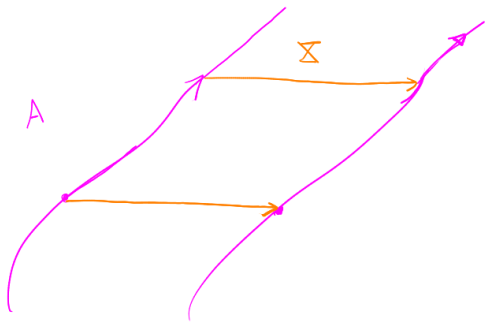


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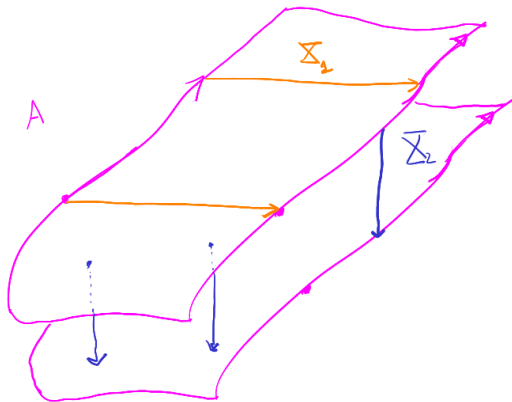


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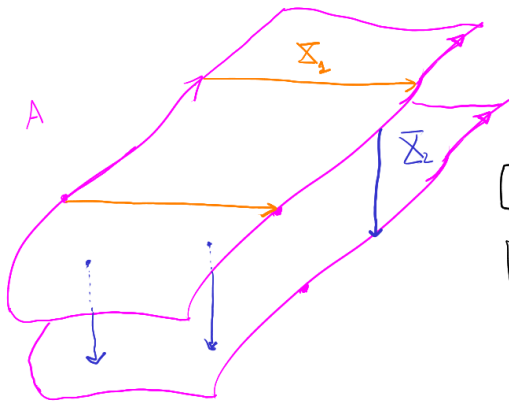
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Idea



$$[\Sigma_1, A] = d \cdot A$$

Idea



$$[X_1, A] = \alpha \cdot A$$

$$[X_2, A] = \alpha_{21} A + \alpha_{22} X_1$$

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Main result

[Basarab-Horwath, 1991]

Given an ODE by the vector field A , the knowledge of a solvable structure for A is equivalent to the integrability by quadratures of the equation (locally).

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- Define $\omega_j = \frac{\det(A, X_1, \dots, X_{j-1}, -)}{\det(A, X_1, \dots, X_{j-1}, X_j)}$, which are locally exact (same reasoning).

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- Integrate and restrict to hypersurfaces.

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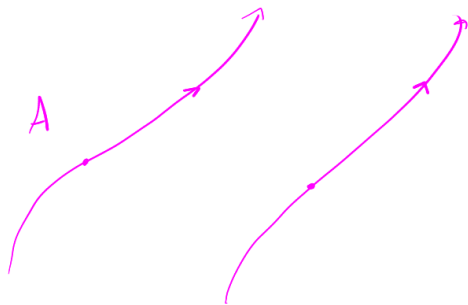
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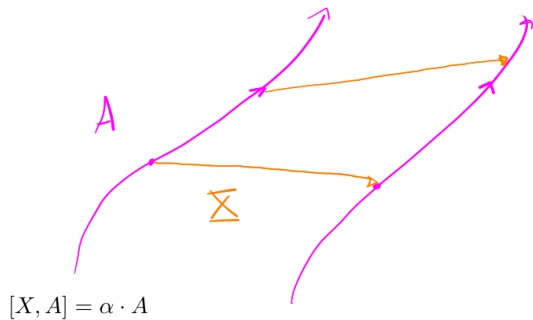
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Or, in other words, there exists a (dynamical) symmetry X such that $Y = \frac{1}{f}X$.

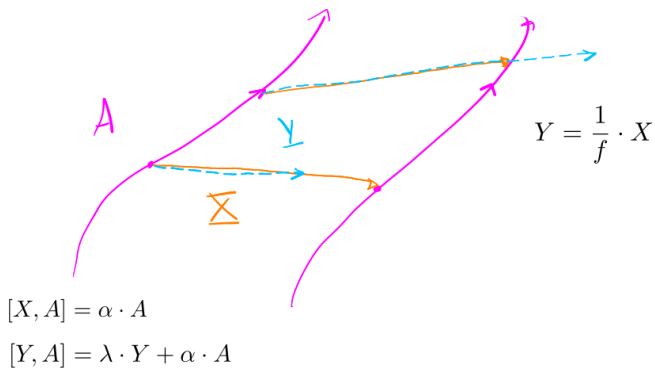
Visual idea



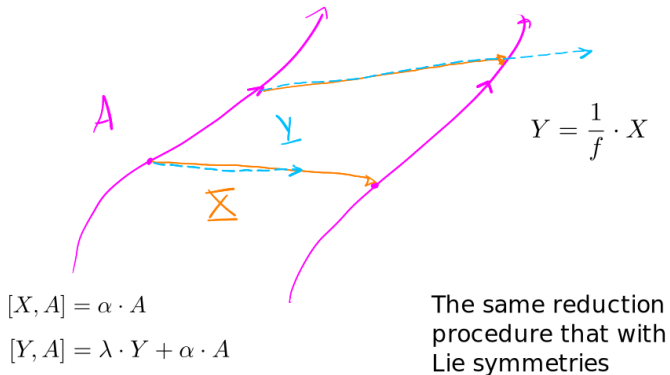
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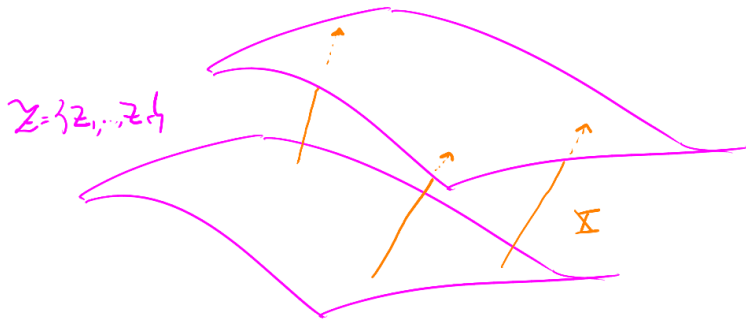


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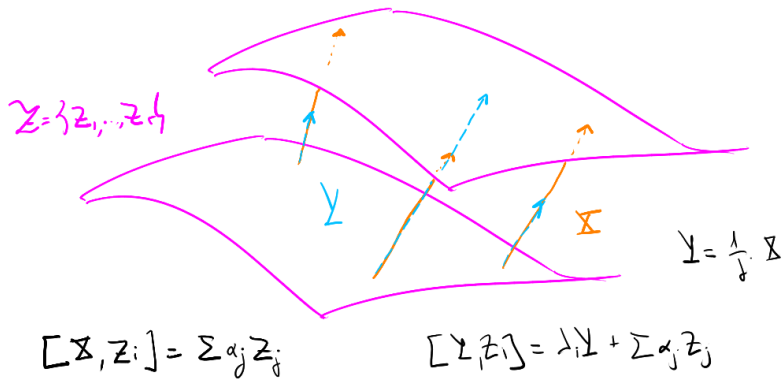


Visual idea



In progress: C^∞ -symmetry of a distribution

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- After m steps we arrive to the solution of the ODE.

Bibliography

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