

CONTROL OF  
SWITCHED  
SYSTEMS AND  
ITS  
APPLICATIONS  
TO  
CONVERTERS

C. PÉREZ

INTRODUCTION  
TO SWITCHED  
SYSTEMS

METHOD FOR  
STABILIZATION  
WHEN  $n = 2$   
AND  $N = 2$

CONTROL FOR  
 $n = 2$  AND  
 $N = 2$

APPLICATION  
TO  
CONVERTERS

## A NEW SITUATION

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Problem: how can we define a switching law  $\sigma$  such that the solution of the switched system converge to  $x_r$ ?

- 1 INTRODUCTION TO SWITCHED SYSTEMS
  - Definition
  - Stability
- 2 METHOD FOR STABILIZATION WHEN  $n = 2$  AND  $N = 2$
- 3 CONTROL FOR  $n = 2$  AND  $N = 2$
- 4 APPLICATION TO CONVERTERS

## CONTROL FOR $n = 2$ AND $N = 2$

Fixed  $x_r \in \mathbb{R}^2$ , the objective is, given an initial condition  $x_0 \in \mathbb{R}^2$ , to define a switching law  $\sigma$  such that

$$\lim_{t \rightarrow \infty} \phi(t; x_0, \sigma) = x_r$$

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- We again define the set  $\{x \in \mathbb{R}^2 : \det(f_1(x), f_2(x)) = 0\}$ .

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For  $i = 1, 2,$

$$G_i(x) = \det(x - x_r, f_i(x))$$

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- $DG_i(x_r) = f_i(x_r) \neq (0, 0)$  because  $x_r$  is not an equilibrium point of the subsystem  $f_i$ .



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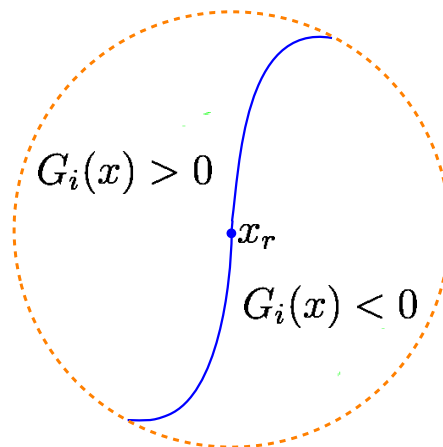
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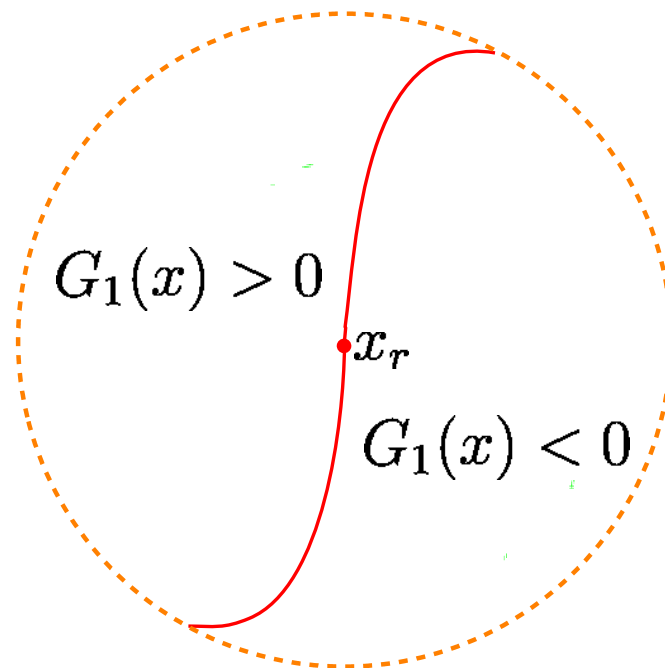
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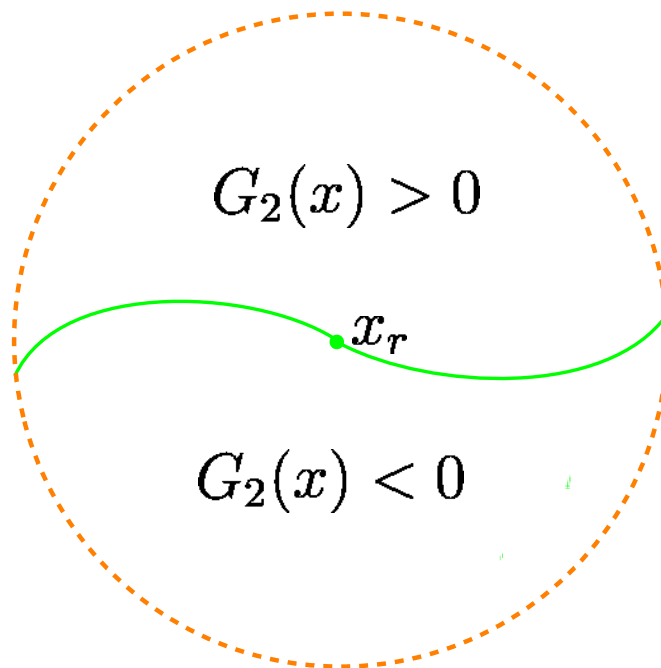
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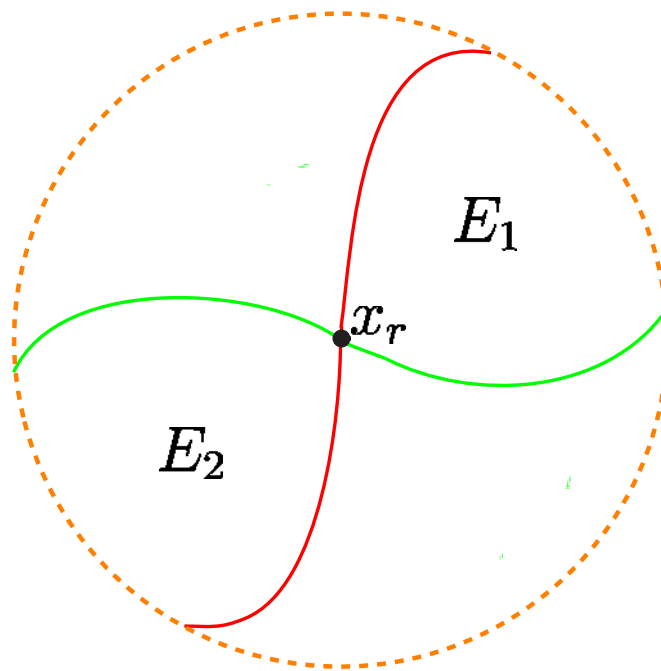
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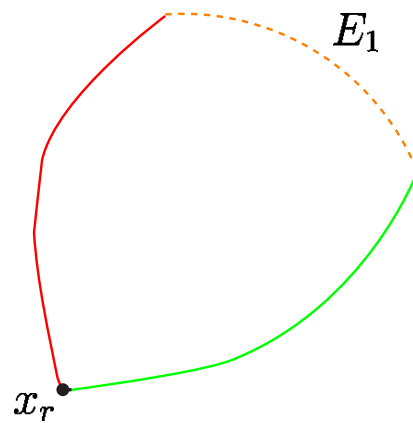


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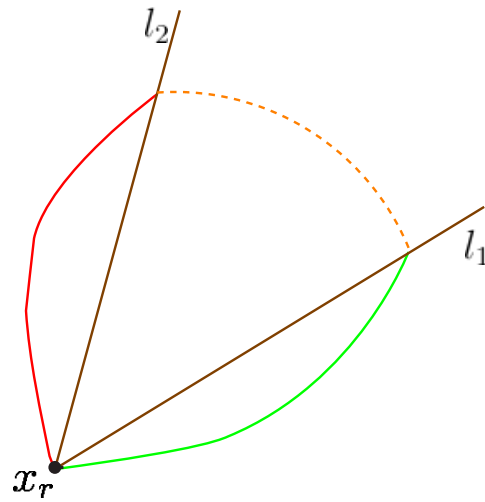
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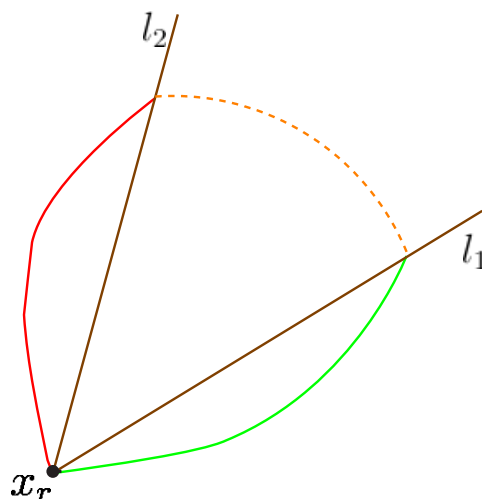
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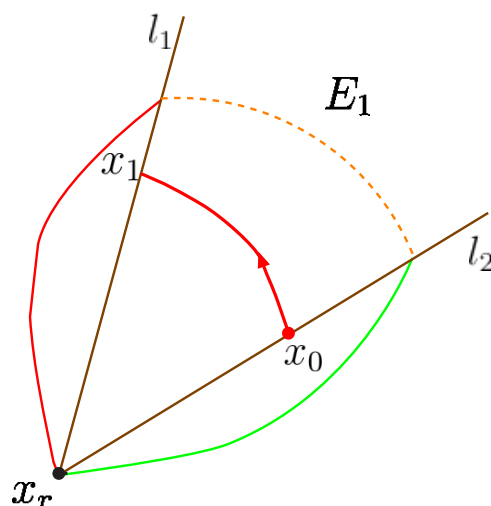
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The set given by

$\{x \in \mathbb{R}^2 : x = x_r + \mu z_1 + (1 - \mu)z_2, z_1 \in l_1, z_2 \in l_2, 0 < \mu < 1\}$   
will be called the cone delimited by  $l_1$  and  $l_2$  and denoted by  $C(x_r, l_1, l_2)$ .



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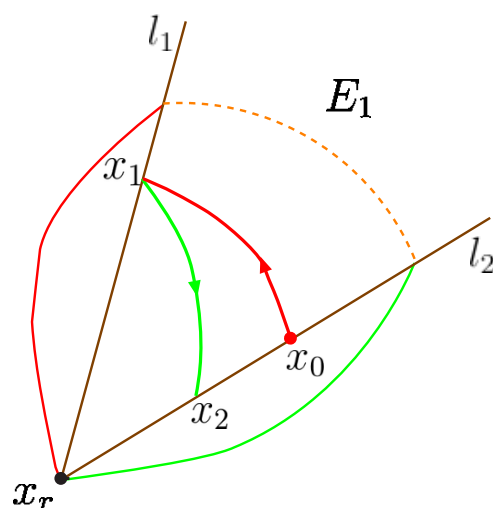


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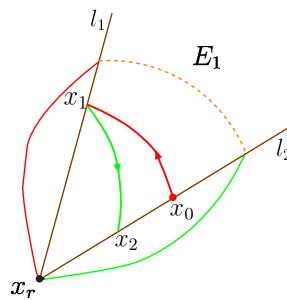
## RESULTS ABOUT CONTROL

### LEMMA

We suppose that:

- $C(x_r, l_1, l_2) \cap \mathcal{U} \setminus \{x_r\} \subset \{x \in \mathbb{R}^2 : \det(f_1(x), f_2(x)) > 0\} \cap E_1$ ,
- the trajectory  $\mathcal{T}_1$  of  $f_1$  goes from  $x_0 \in l_2$  to  $x_1 \in l_1$  (in counterclockwise direction respect to  $x_r$ ), and
- the trajectory  $\mathcal{T}_2$  of  $f_2$  goes from  $x_1 \in l_1$  to  $x_2 \in l_2$  (in clockwise direction respect to  $x_r$ ),

then it holds that  $\|x_2 - x_r\| < \|x_0 - x_r\|$ .



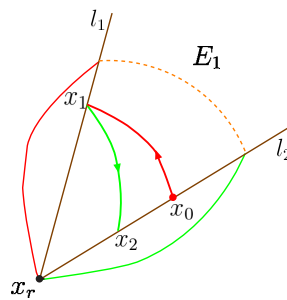
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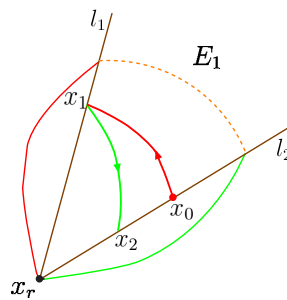
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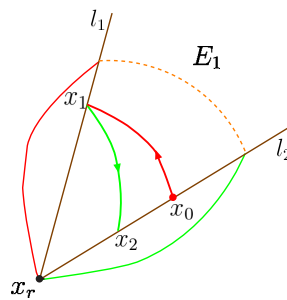
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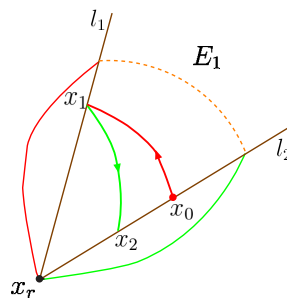
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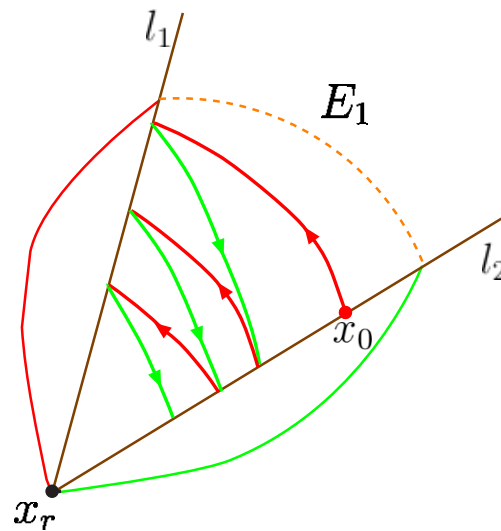
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### THEOREM

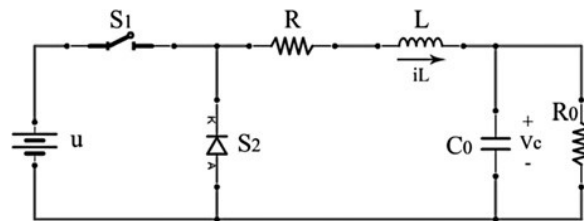
*If  $E_1 \cap \{x \in \mathbb{R}^2 : \det(f_1(x), f_2(x)) > 0\} \neq \emptyset$ , then there exists a cone  $C(x_r; l_1, l_2)$  such that for each initial condition  $x_0 \in C(x_r; l_1, l_2)$  there exists a switching law  $\sigma$  such that the solution of the switched system starting from  $x_0$  converge to  $x_r$ .*





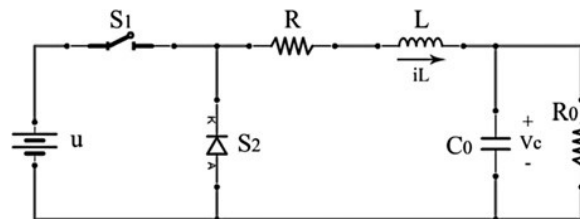
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- $v_C$  is the capacitor voltage.
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$$\dot{x} = \begin{pmatrix} -R/L & -1/L \\ 1/C_0 & -1/(R_0 C_0) \end{pmatrix} x + \begin{pmatrix} 1/L \\ 0 \end{pmatrix} u$$

When  $S_1$  is OFF,

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- The objective is obtain a switching strategy  $\sigma$  under which the output voltage converges to the desired reference.

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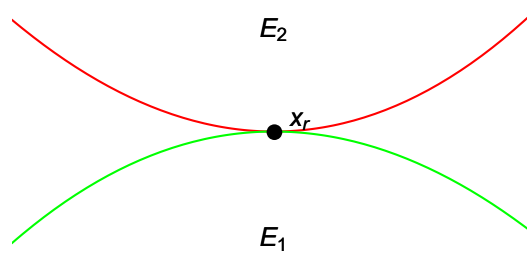
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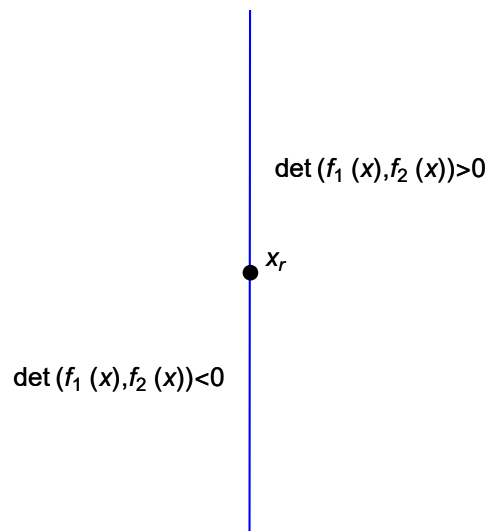
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- The sets  $E_1$  and  $E_2$ .
- The set of  $\{x \in \mathbb{R}^2 : \det(f_1(x), f_2(x)) = 0\}$  is a ray.
- Thus,

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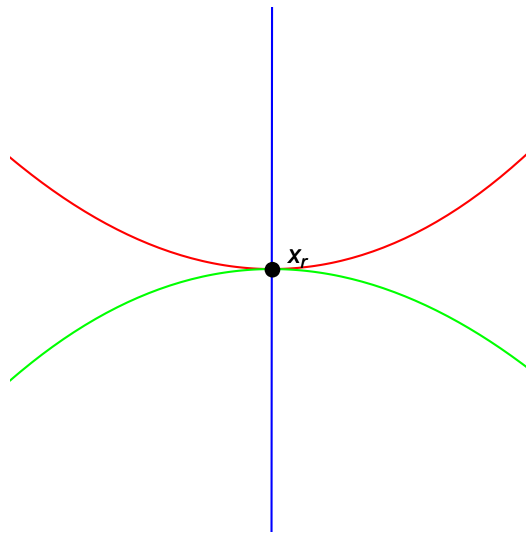
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- The set of  $\{x \in \mathbb{R}^2 : \det(f_1(x), f_2(x)) = 0\}$  is a ray.
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ITS  
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C. PÉREZ

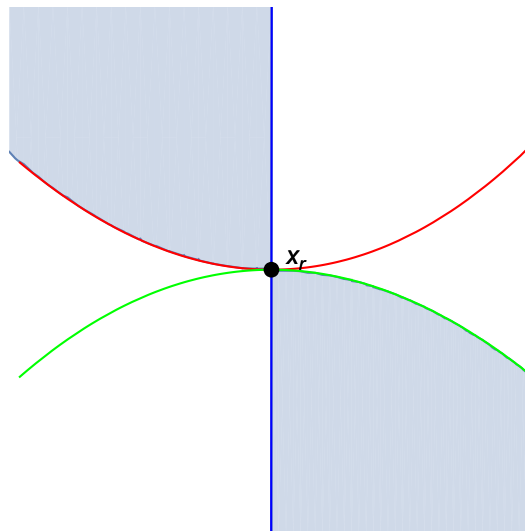
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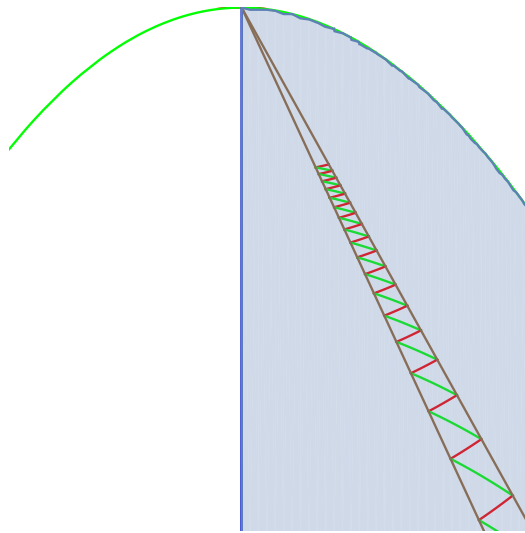
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## NUMERICAL EXAMPLE

- $L = 500\mu H$ ,  $C_0 = 470\mu F$ ,  $u = 100V$ ,  $R = 2\Omega$ , and  $R_0 = 50\Omega$  (values in Noori et al (2016)).

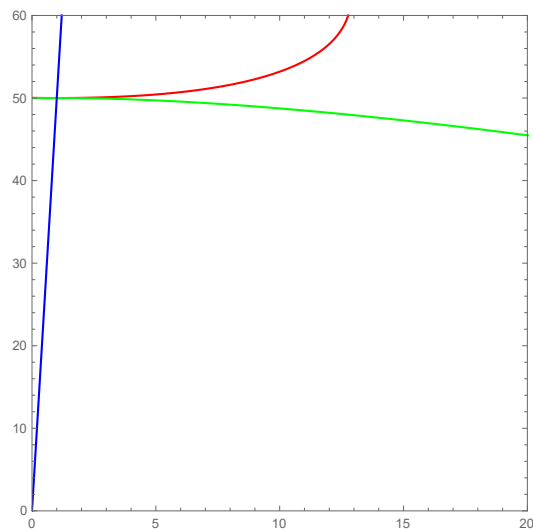
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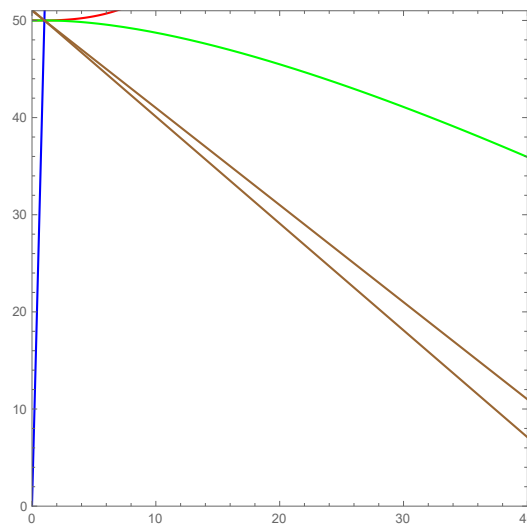
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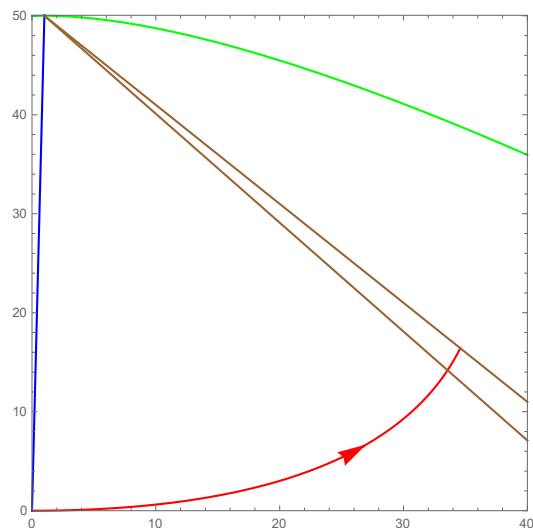


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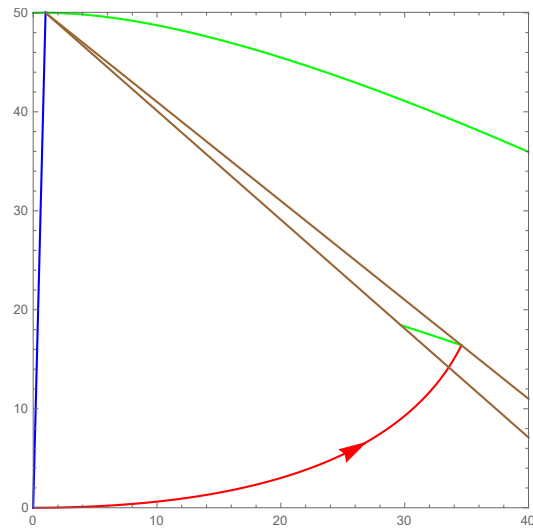
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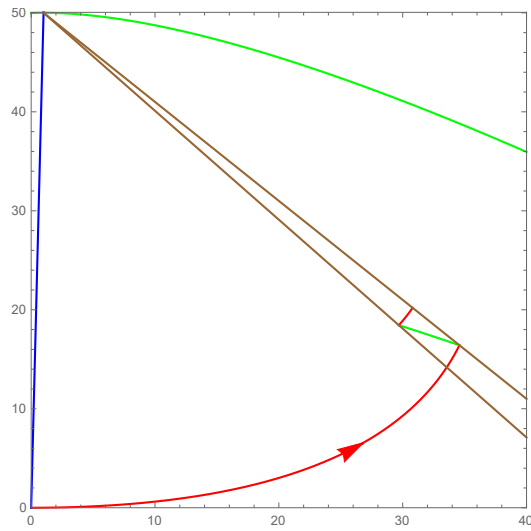
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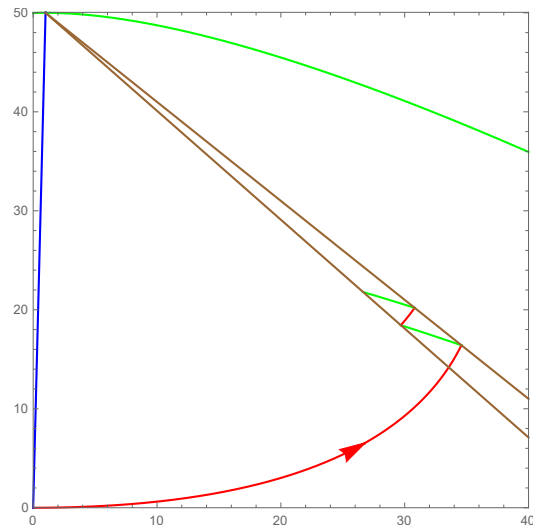
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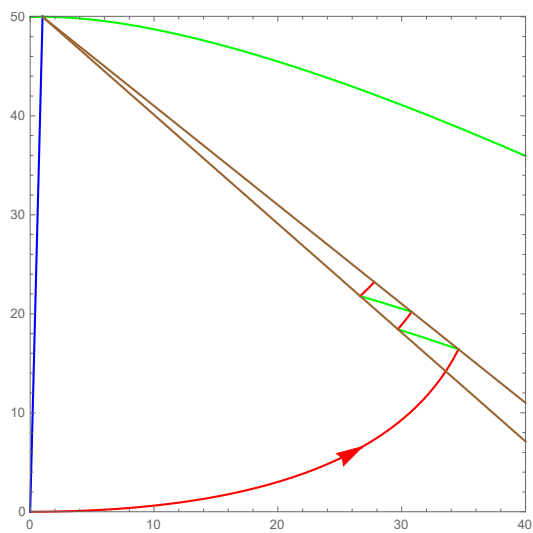
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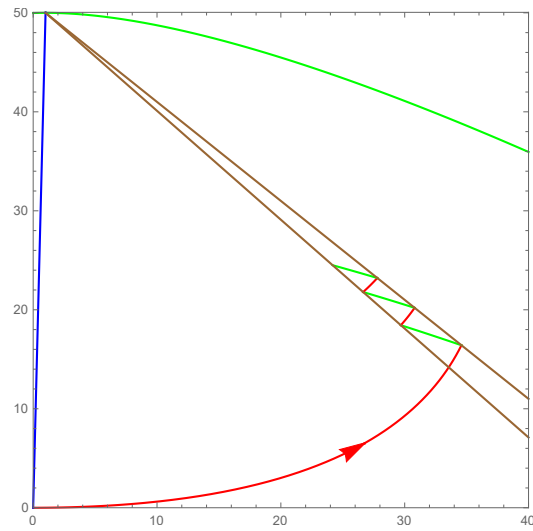


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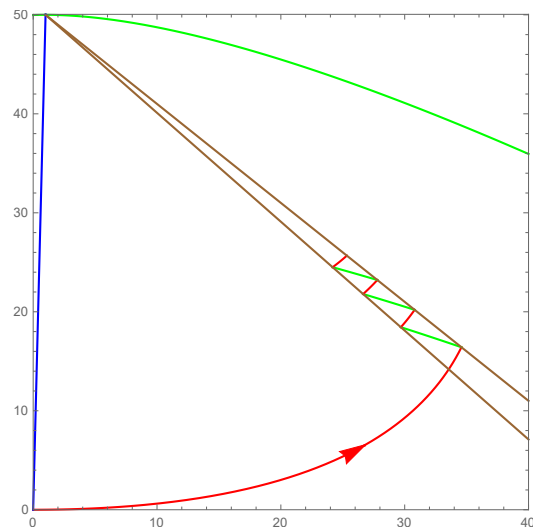




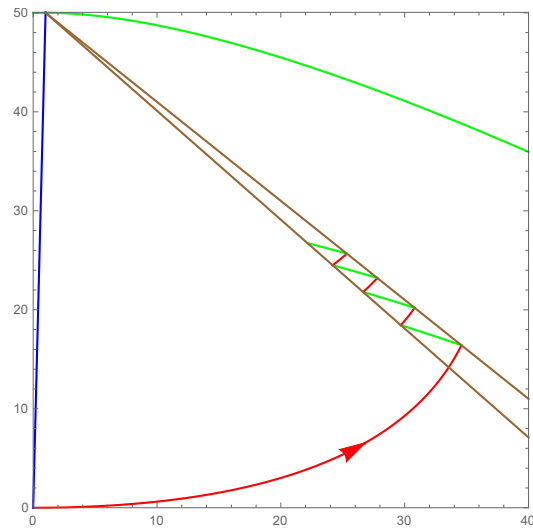
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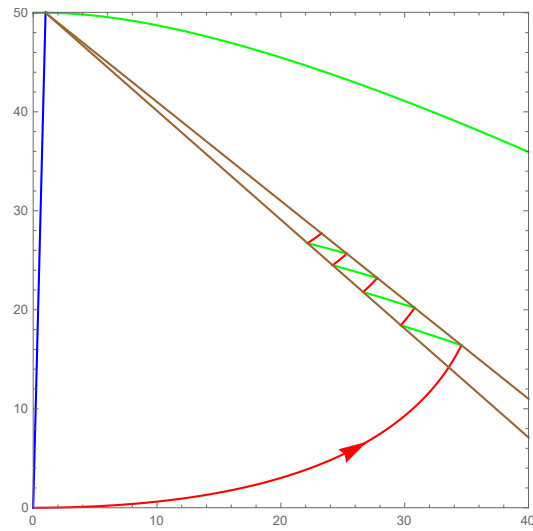
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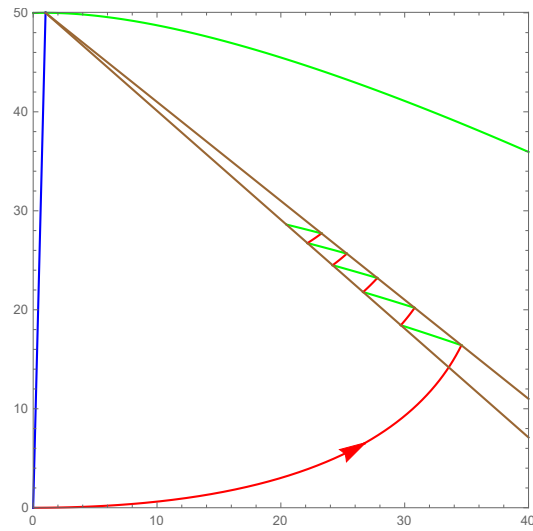
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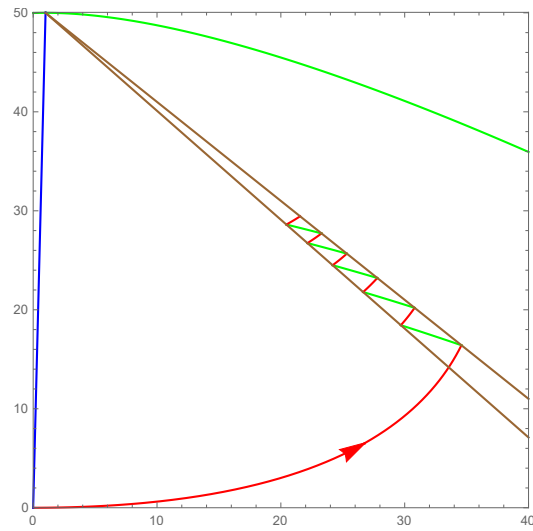
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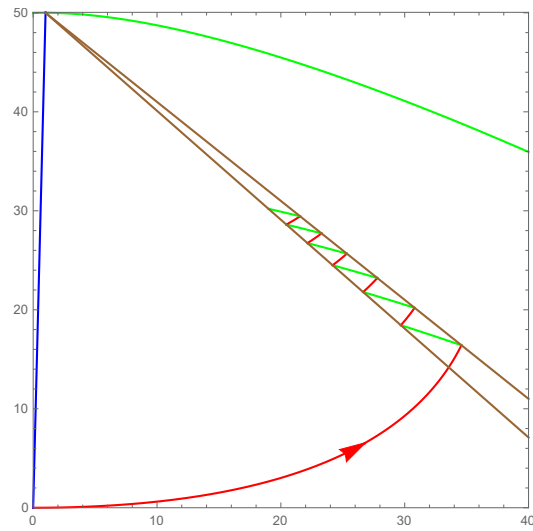
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Thank you for your  
attention!